

3D Mesh and Lidar Point Clouds

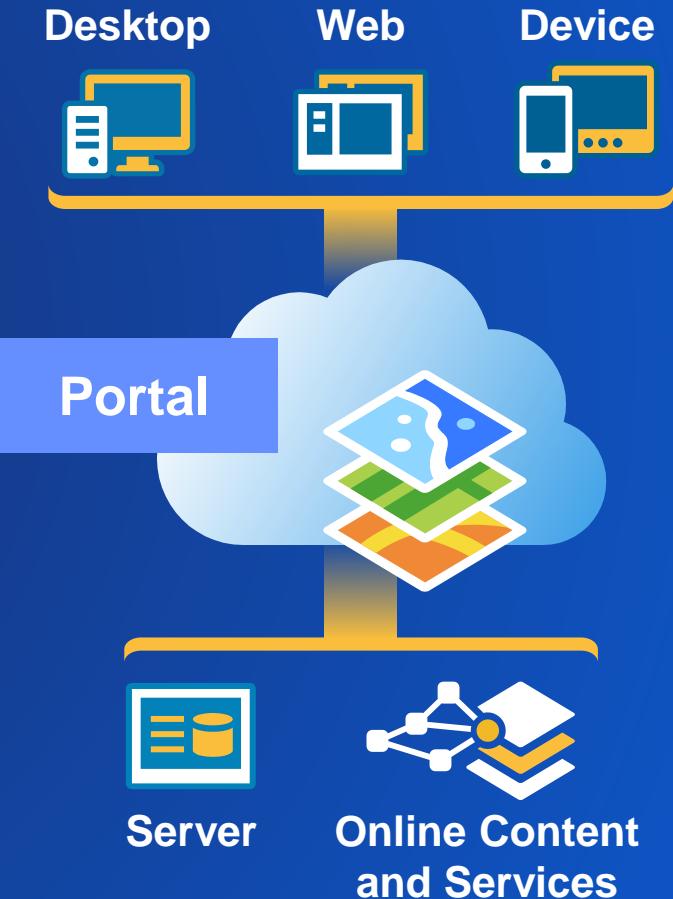
Lindsay Weitz: 3D Product Engineer, 3D Analyst

Seán William Morrish: 3D Product Engineer, Scene Layers



3D GIS Platform

- Synthesize 2D and 3D in web **GIS** architecture
- Default Elevation Service
- Multiuse dynamic services across clients
- Securely manage large enterprise geodatabases
- Analyze across real-time and historical data



ArcGIS 3D Scene Layers

- 3D Objects Scene Layer
- 3D Point Scene Layer
- 3D Integrated Mesh Layer
- 3D Point Cloud Scene Layer
- 3D Building Scene Layer
- Elevation Layer



Content Profiles

- Support different geometry types

- Individual Features

- Points
 - Multipatches

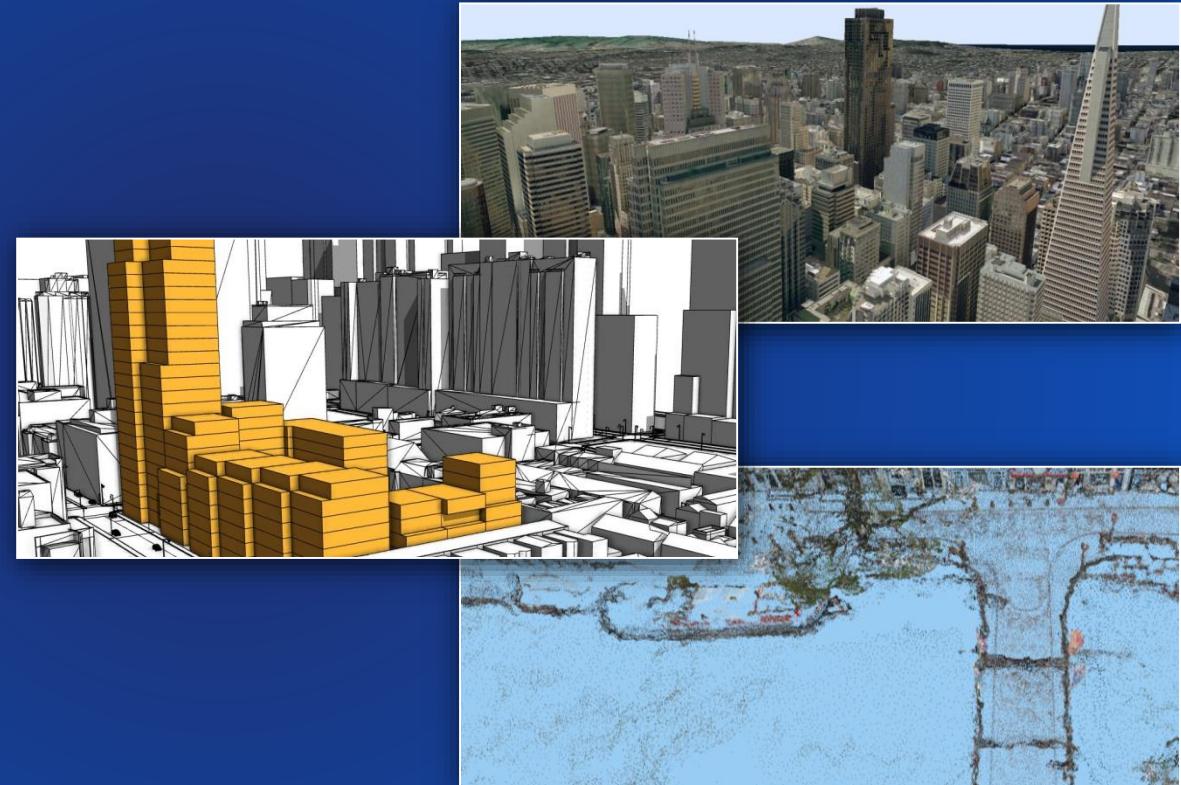
- Integrated Meshes

- Pointclouds

- Point Symbols

- Building Layers

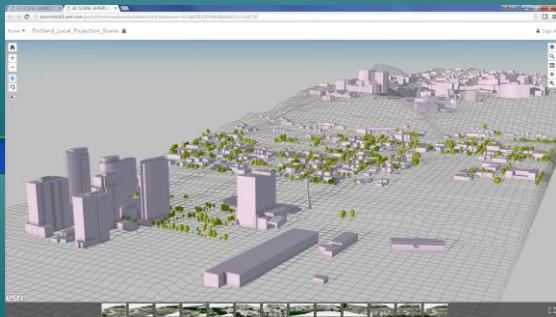
- Analytics



Parts of a Scene



Feature Service Layers



2D Layers
Draped or *Absolute**

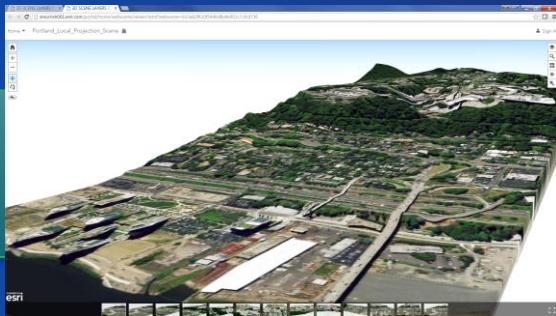
Feature Service Layers

Web Scene Layers
(i3S)



Web Scene Layers
(i3S)

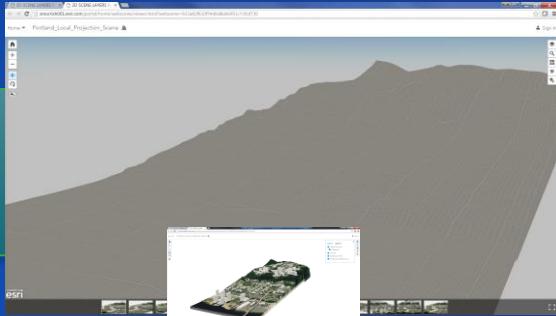
Your Local Imagery



Draped Imagery

ArcGIS Online

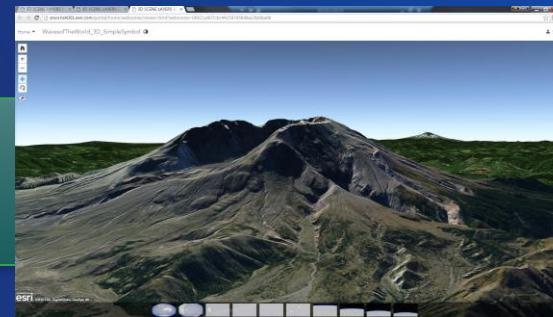
Your Local Terrain



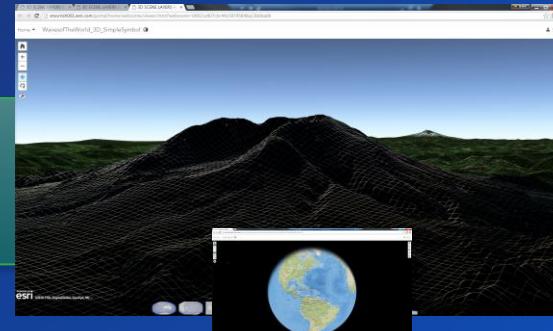
Terrain

ArcGIS Online

Local Scene



Global Scene

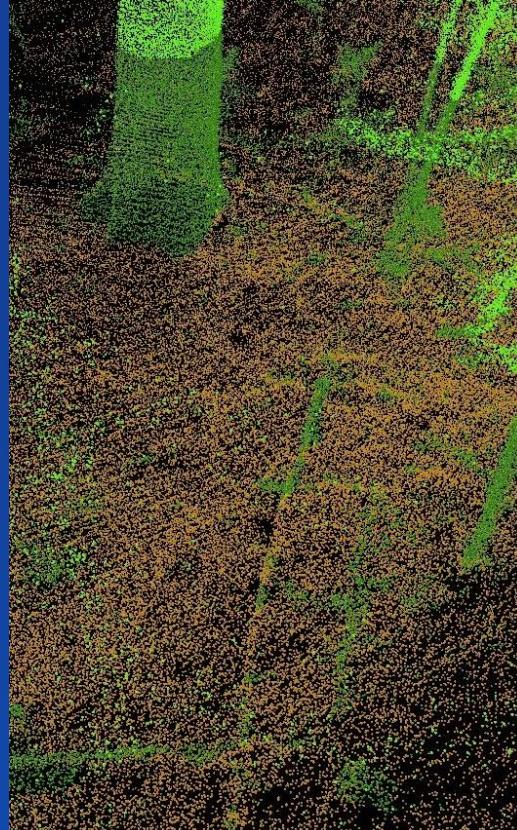


ArcGIS Supports

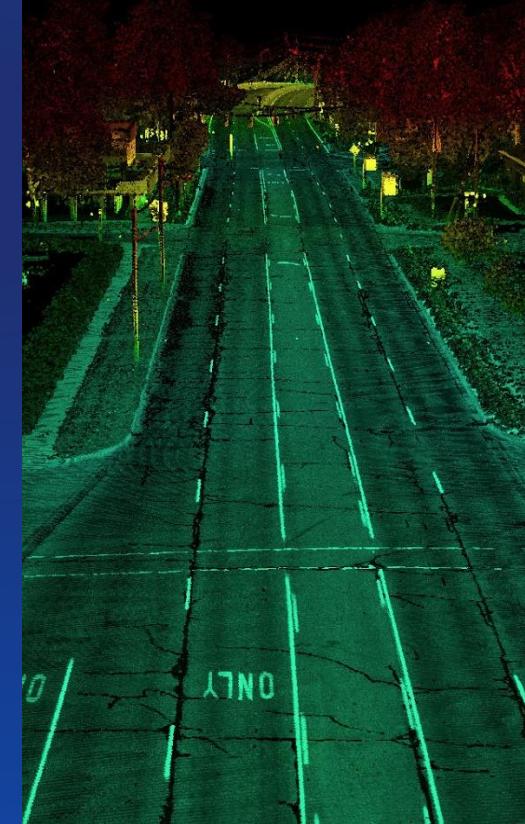
Airborne



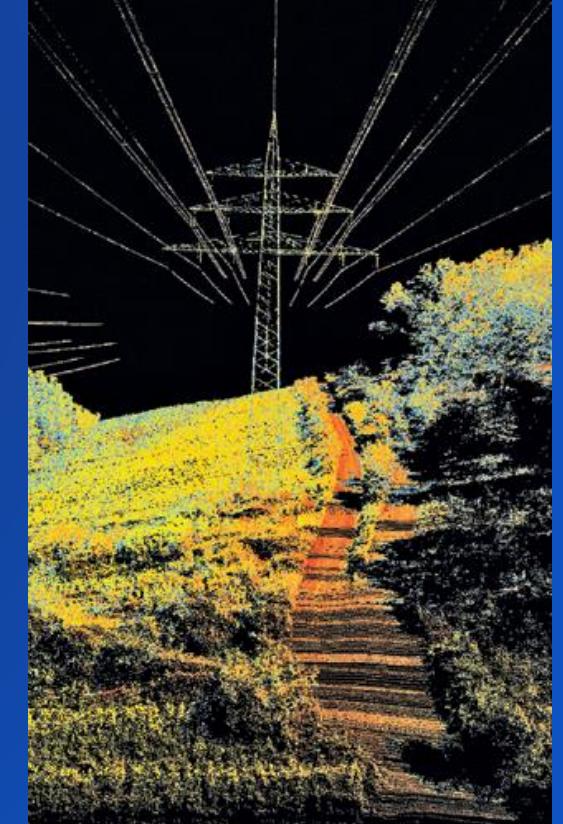
Terrestrial



Mobile



Drone/UAV



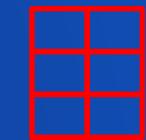
Data Structures for lidar support in ArcGIS



File01.las
File02.las
...
File99.las

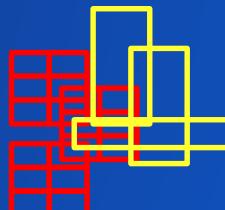
Multiple
files/folders

Analyze and Update



**LAS dataset /
Terrain dataset**

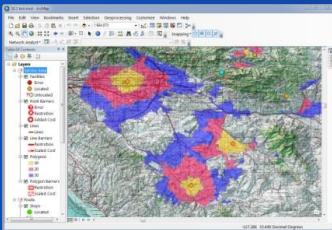
Manage and Share



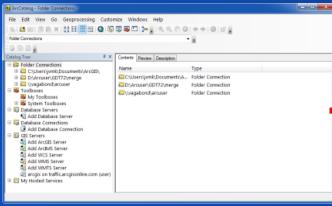
**Mosaic dataset /
Point cloud scene
layer**

Application Fusion: ArcGIS Pro

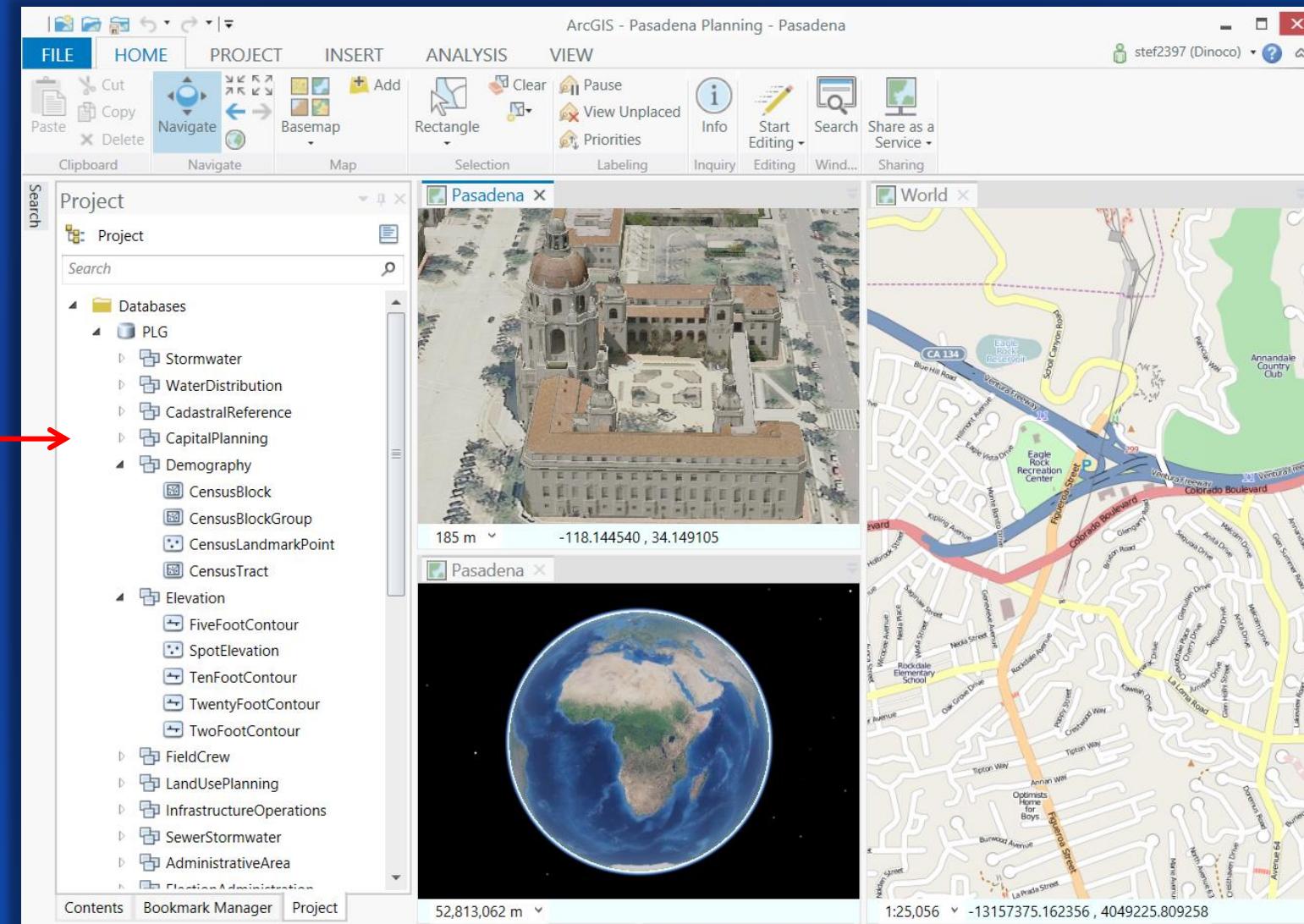
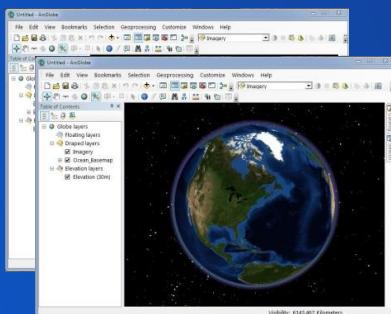
ArcMap



ArcCatalog

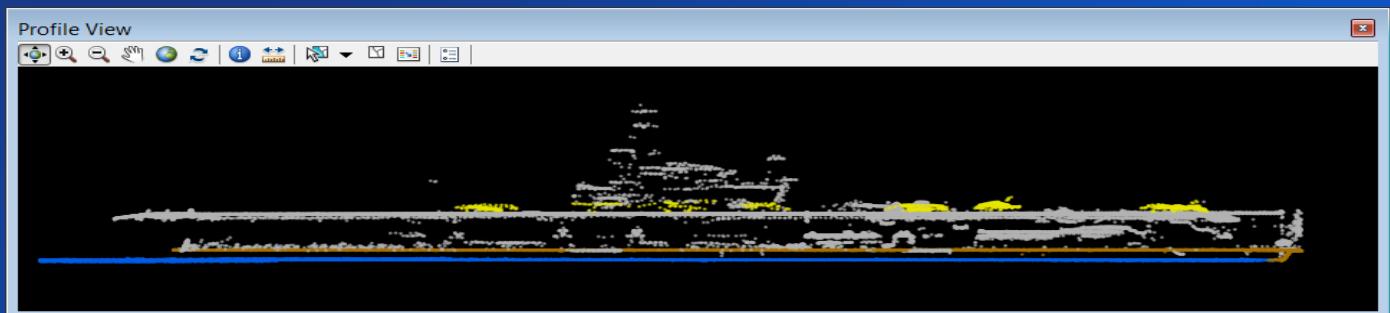
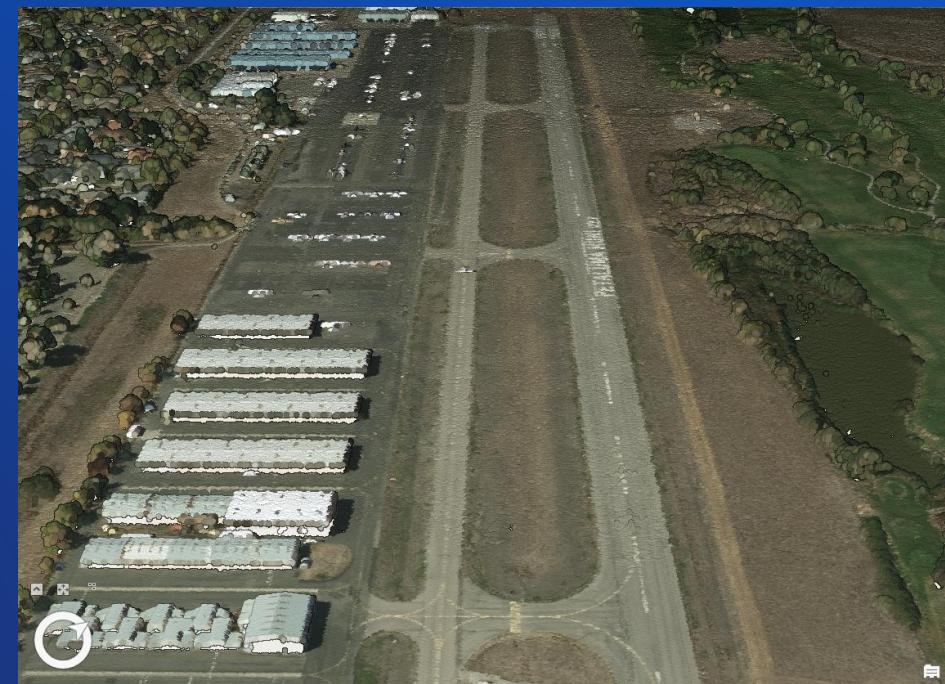


ArcGlobe / ArcScene

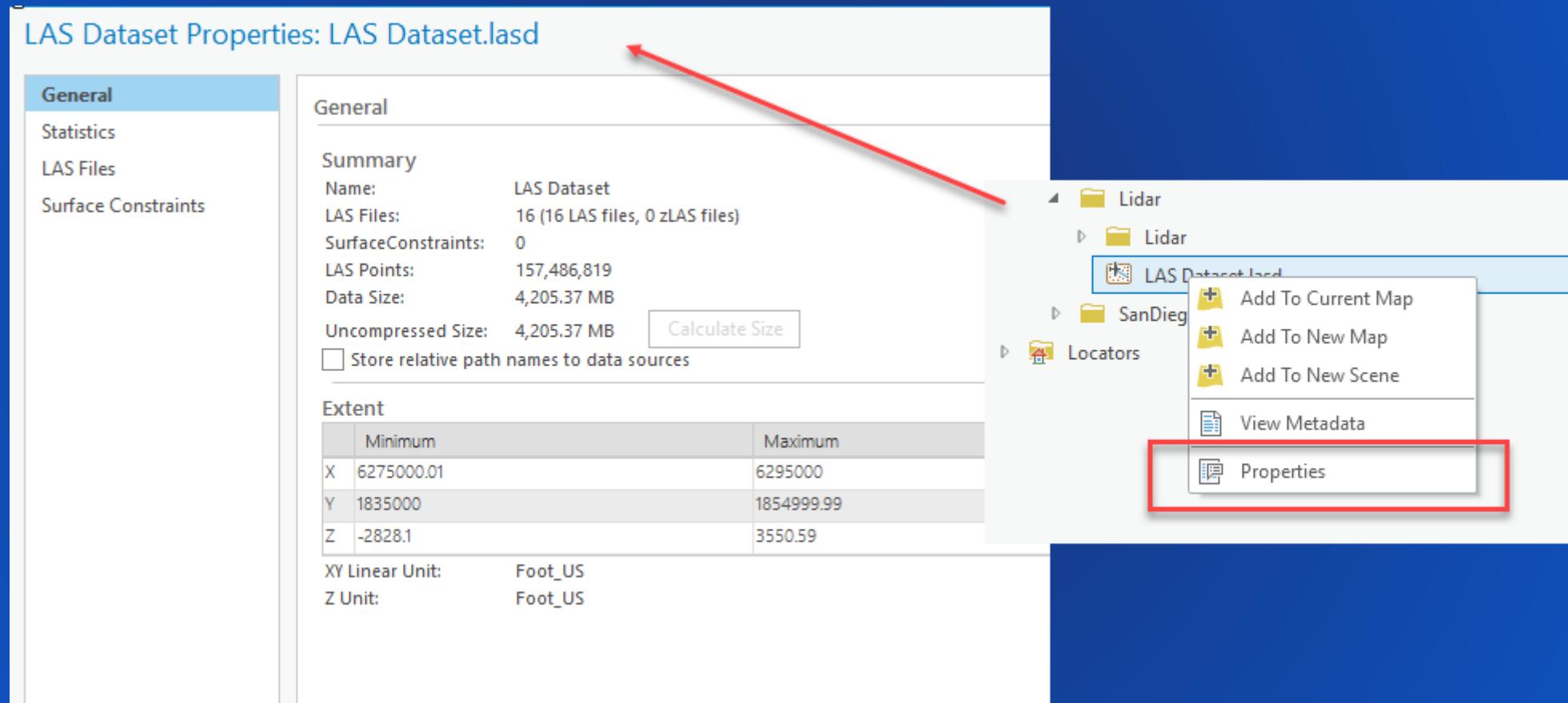


Lidar data with a LAS dataset

- Direct read of LAS or zLAS format lidar
- File based
- QA/QC tools
- Stores references to LAS/zLAS files on disk
- Optionally reference breakline and control point data
- Treats a collection of LAS/zLAS files as one logical dataset (“Project”)



LAS Dataset Properties



The screenshot shows the 'LAS Dataset Properties' dialog for 'LAS Dataset.lasd' and a context menu for the same dataset.

LAS Dataset Properties: LAS Dataset.lasd

General

- Statistics
- LAS Files
- Surface Constraints

General

Summary

Name:	LAS Dataset
LAS Files:	16 (16 LAS files, 0 zLAS files)
SurfaceConstraints:	0
LAS Points:	157,486,819
Data Size:	4,205.37 MB
Uncompressed Size:	4,205.37 MB

Store relative path names to data sources

Extent

	Minimum	Maximum
X	6275000.01	6295000
Y	1835000	1854999.99
Z	-2828.1	3550.59

XY Linear Unit: Foot_US
Z Unit: Foot_US

Context Menu (right-clicked on 'LAS Dataset.lasd'):

- Lidar
- Lidar
- LAS Dataset.lasd** (highlighted)
- SanDiego
- Locators
- Properties** (highlighted with a red box)

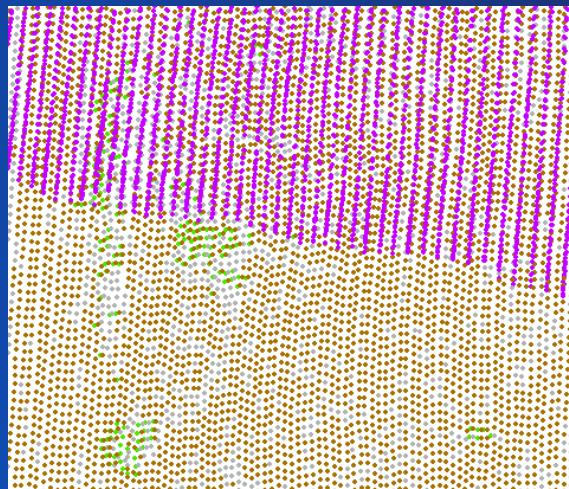
Context Menu Options:

- Add To Current Map
- Add To New Map
- Add To New Scene
- View Metadata

Classify LAS Overlap

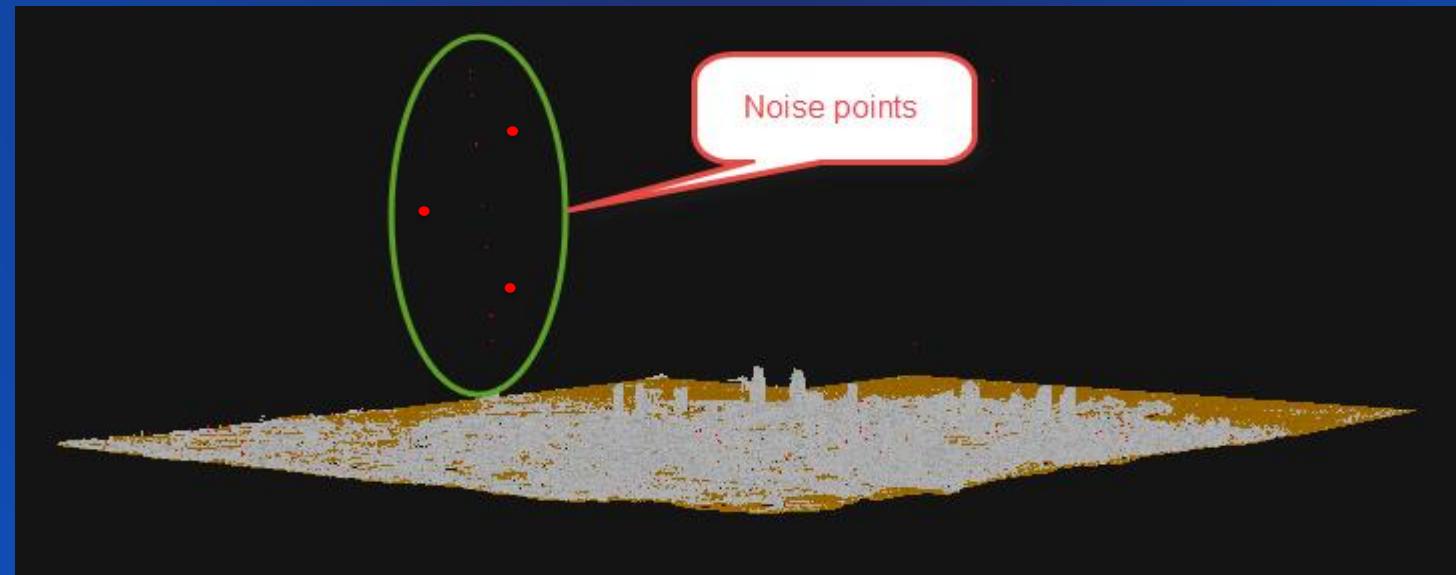
- Geoprocessing tool to assign the overlap flag/code to points in areas of overlap between flight lines.
- Area of overlap introduces high frequency noise to ground which interferes with creation of high quality DEMs. It's therefore desirable to exclude the overlap.
- Tool helps improve quality of DEMs ArcGIS can produce.

Overlap in purple



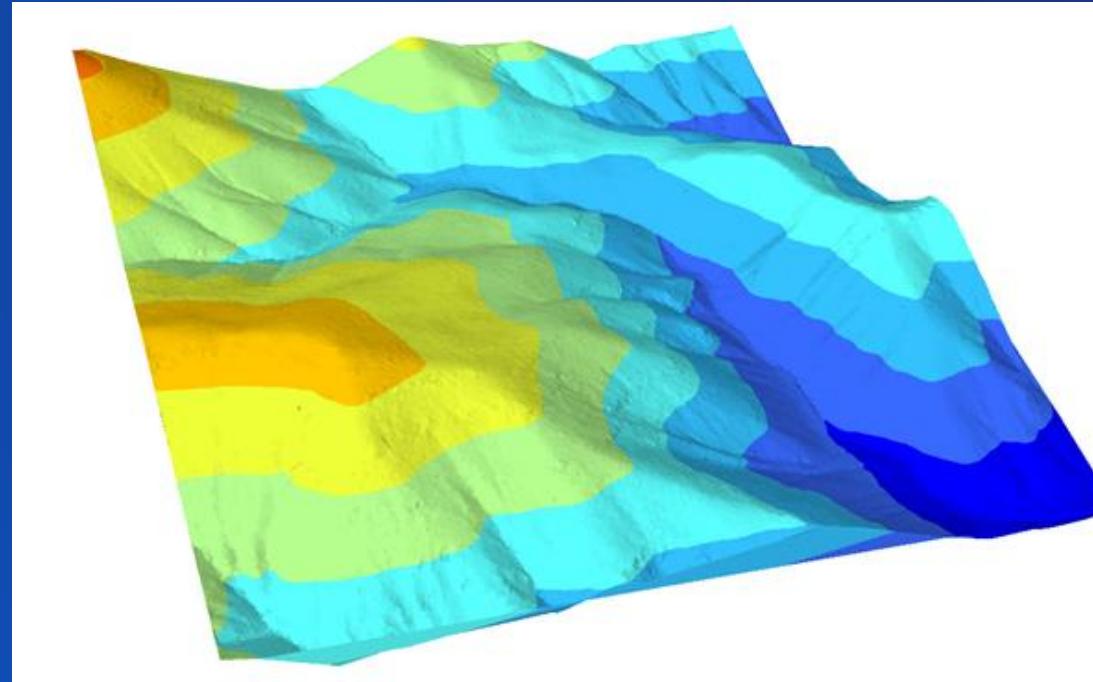
Classify LAS Noise

- Tool to classify noise points in lidar.
- Erroneous points are caused by a variety of things such as haze, birds, and water.
- Present at least to some degree in all lidar collections.
- Noise interferes with display and processing of the data.
- This is a fundamental capability.



Classify LAS ground

- Classifies ground points in lidar data
- Only the last return of LAS points with class code values of 0, 1, or 2 will be considered for reclassification as ground.



Classify LAS Ground

Parameters | Environments

* Input LAS Dataset

Ground Detection Method

Reuse existing ground

DEM Resolution Meters

Compute Statistics

Processing Extent

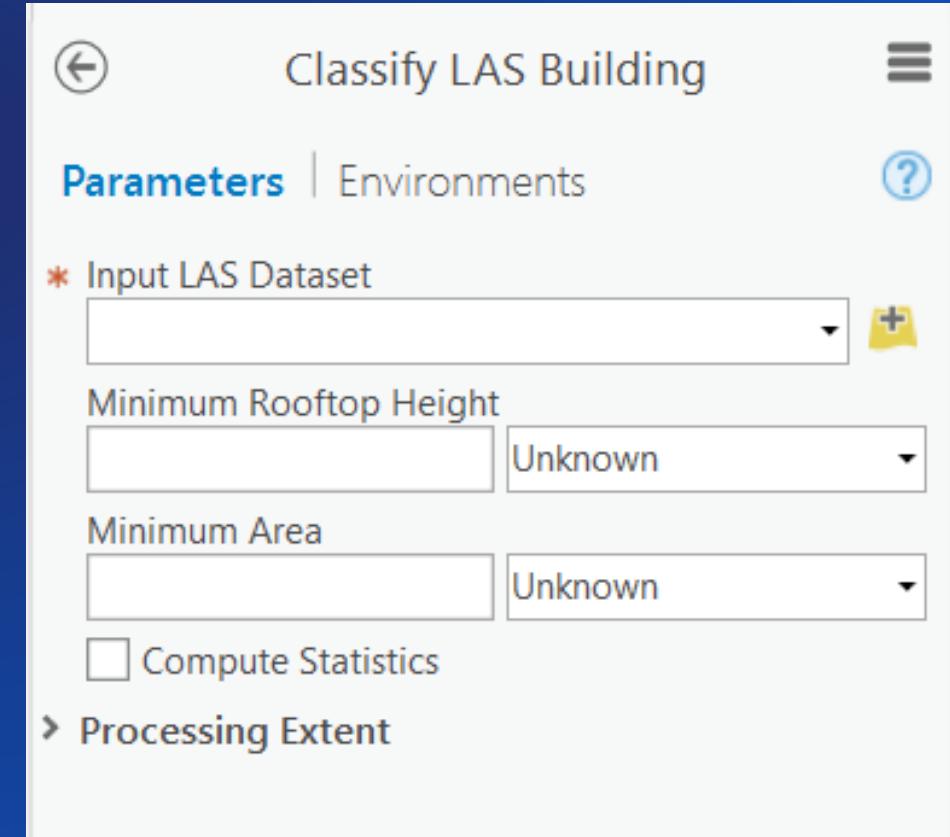
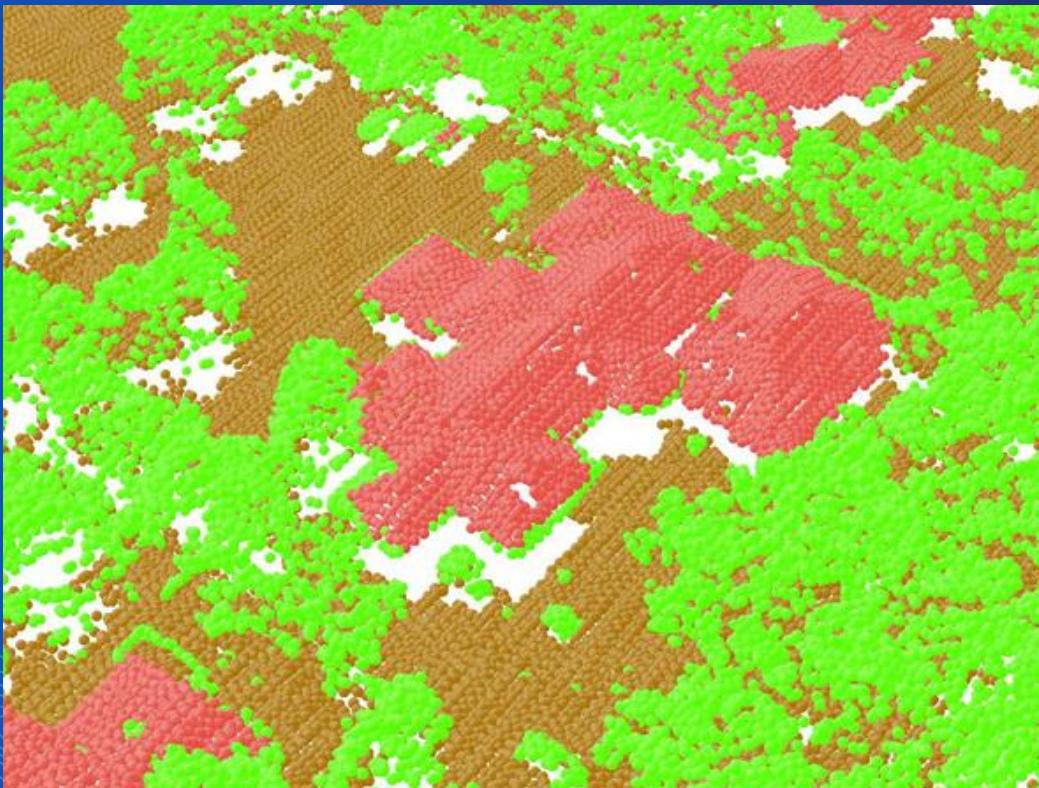
Processing Extent

Processing Boundary

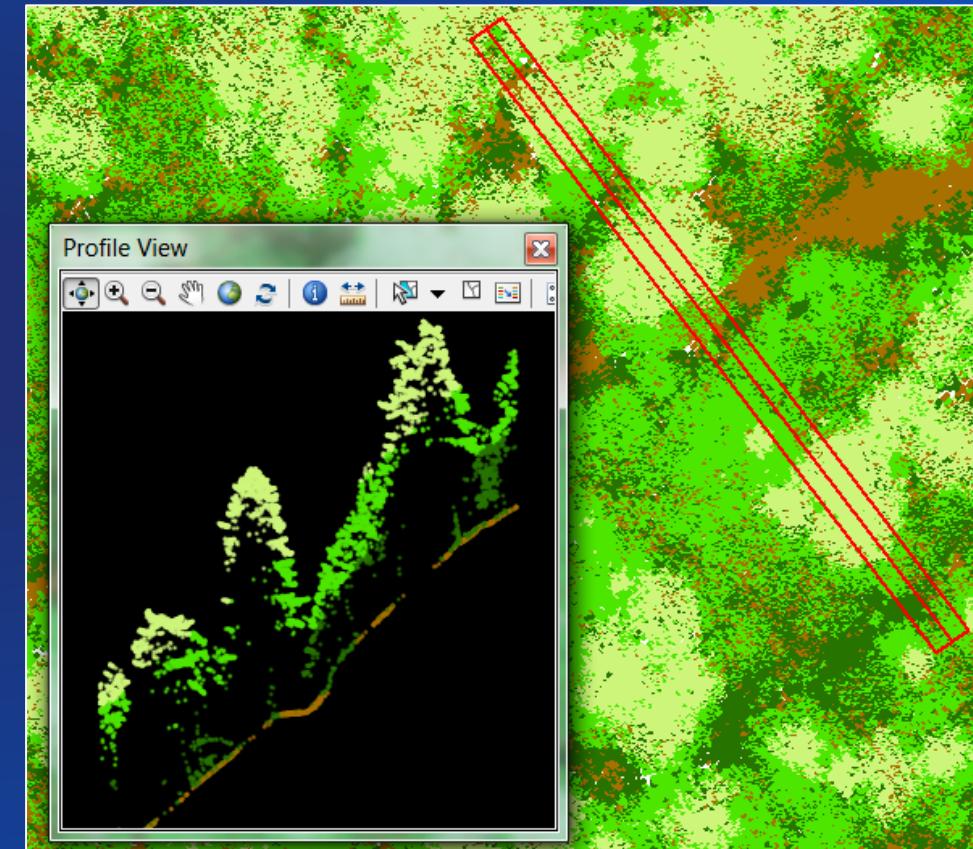
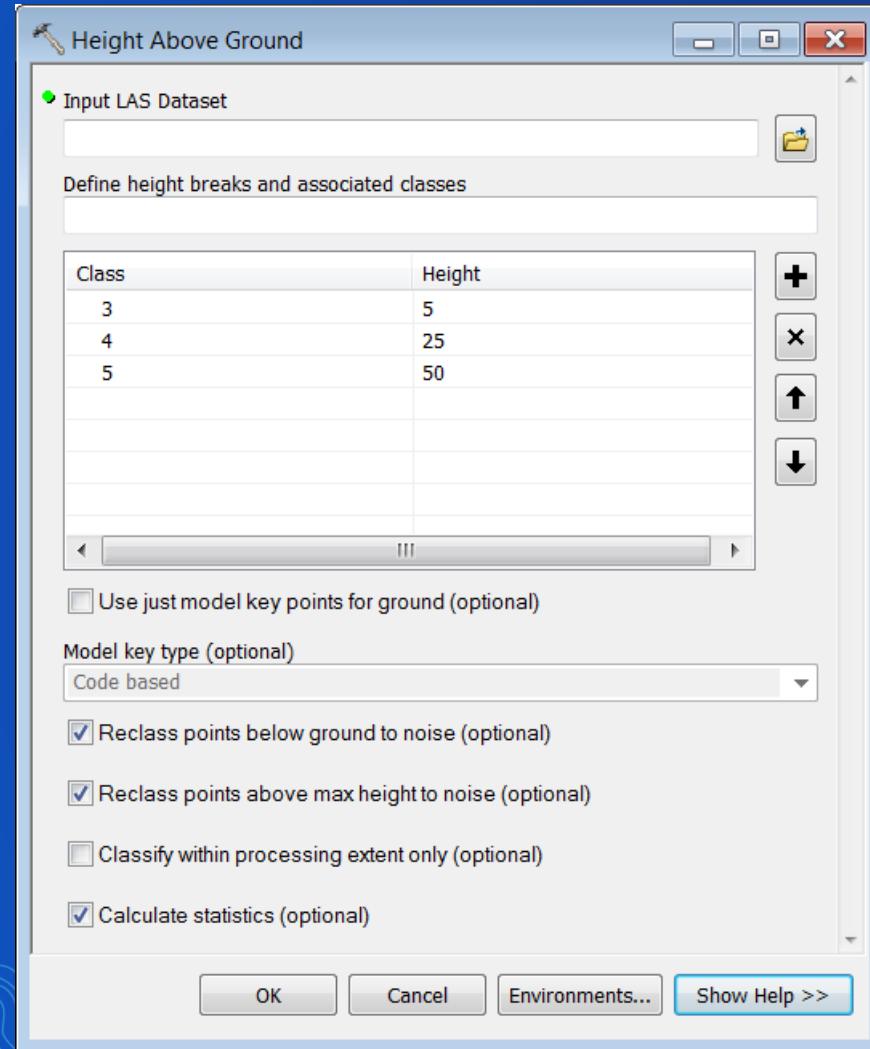
Process entire LAS files that intersect extent

Classify LAS buildings

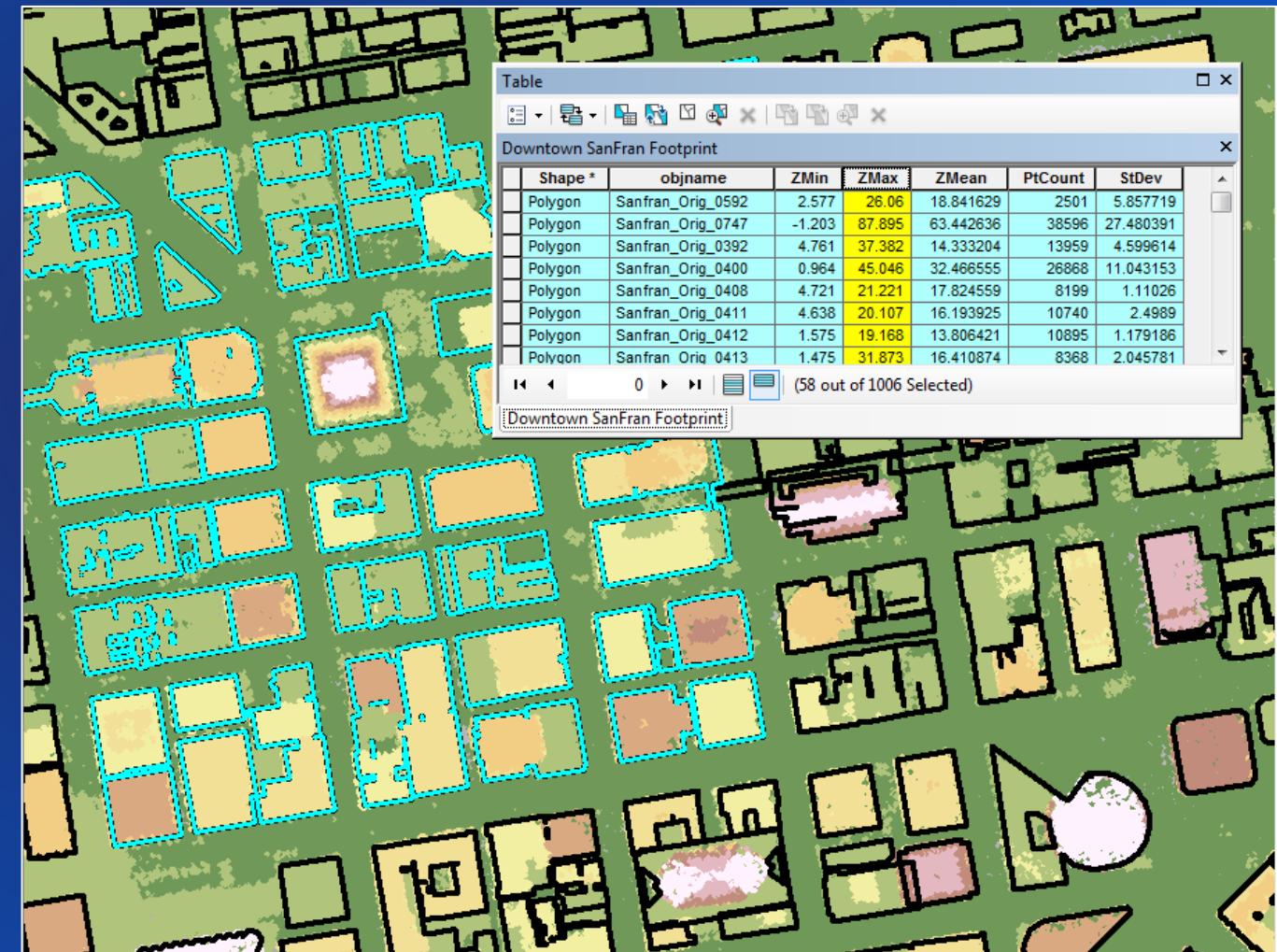
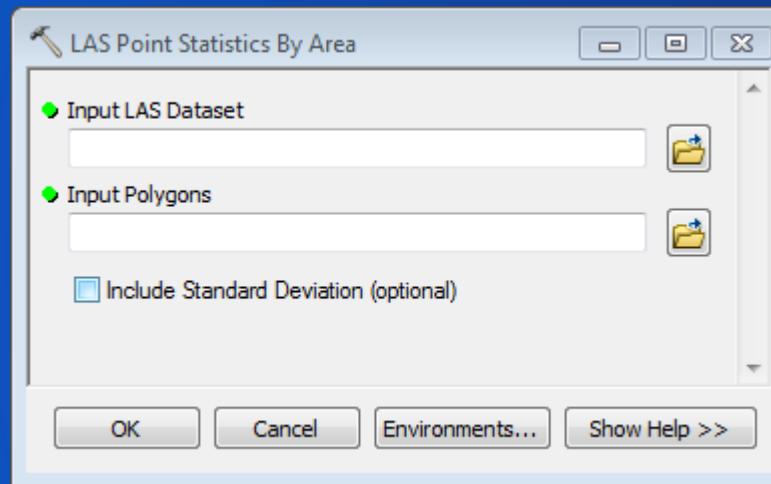
- Classifies building rooftop points in aerial lidar data
- The lidar data must have ground points that are assigned a class code value of 2.



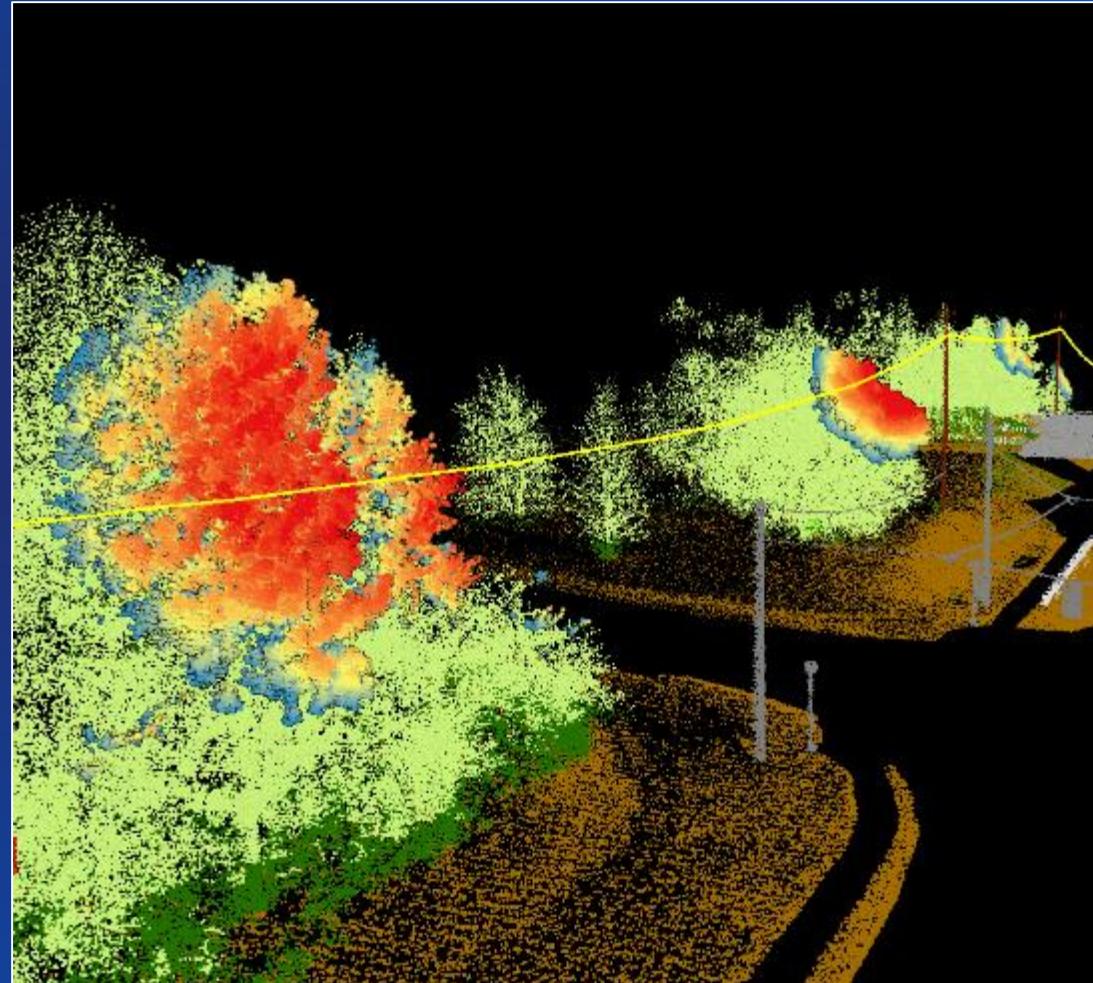
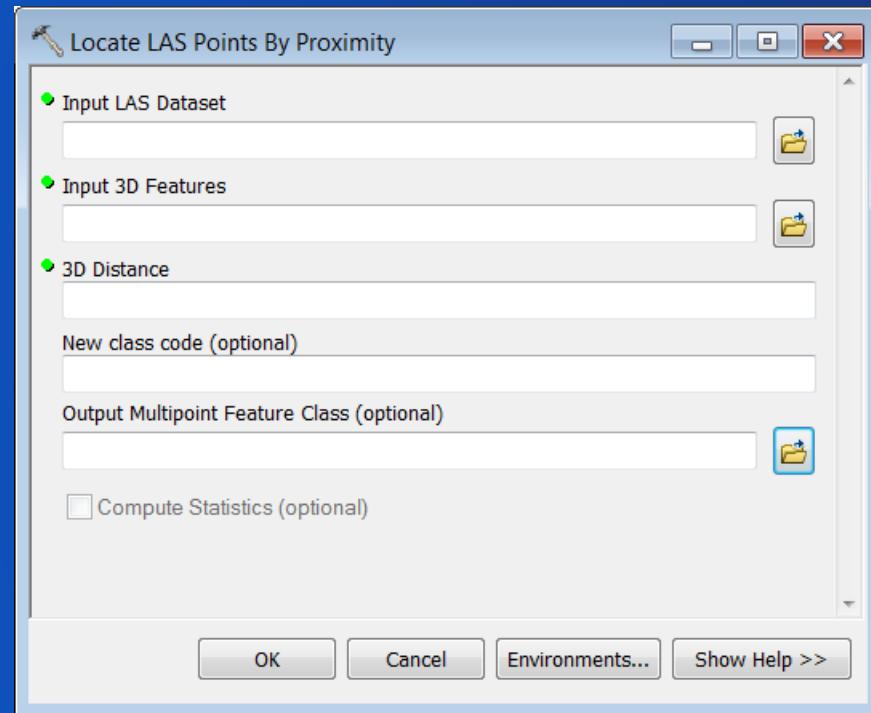
Classify LAS by Height



LAS Point Statistics By Area



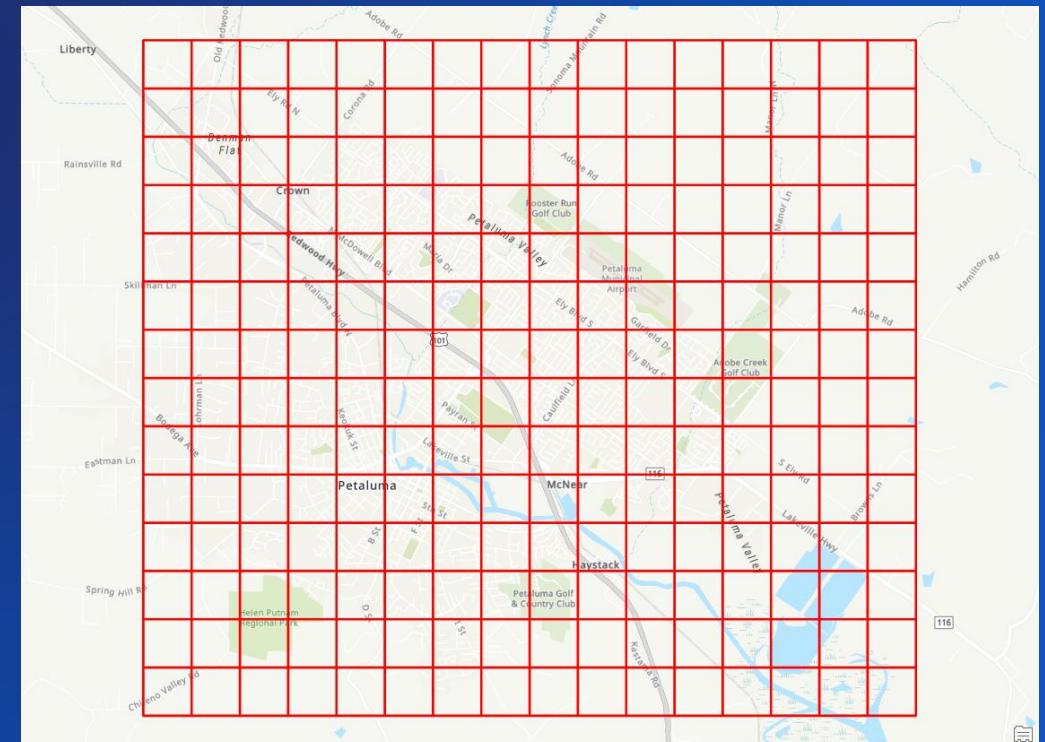
Locate LAS Points By Proximity



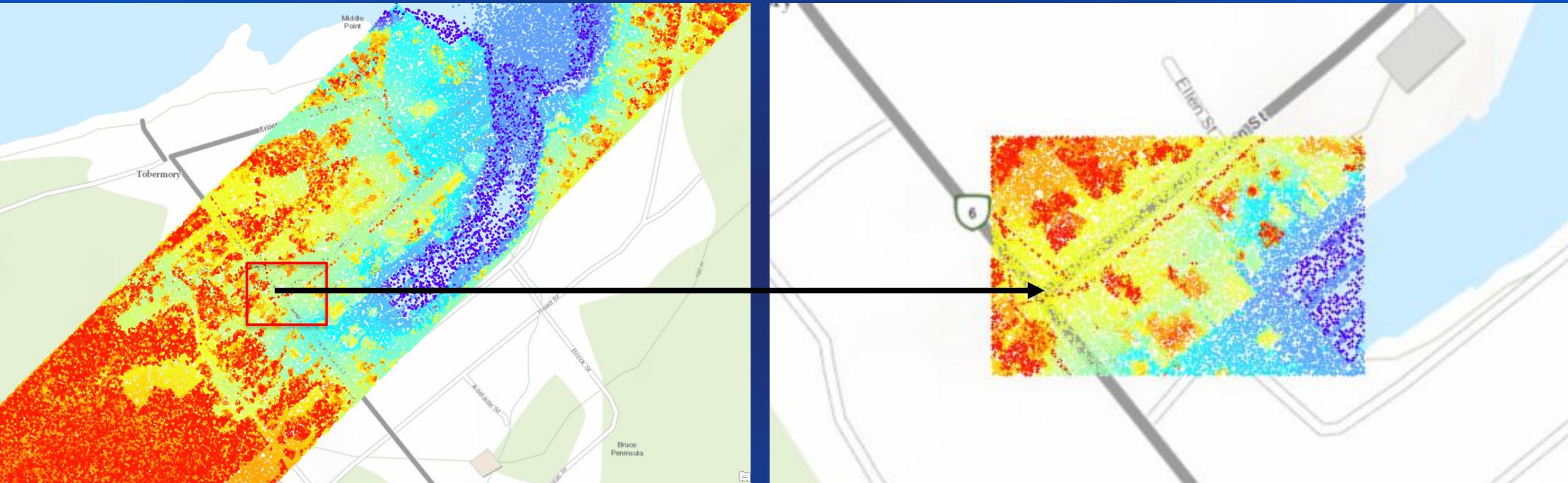
Data courtesy of PhotoScience

Tile LAS

- Creates a set of nonoverlapping LAS files whose horizontal extents are divided by a regular grid.
- Improves performance of operation that rely on reading data in spatial clusters. For example: analysis operations and visualization.



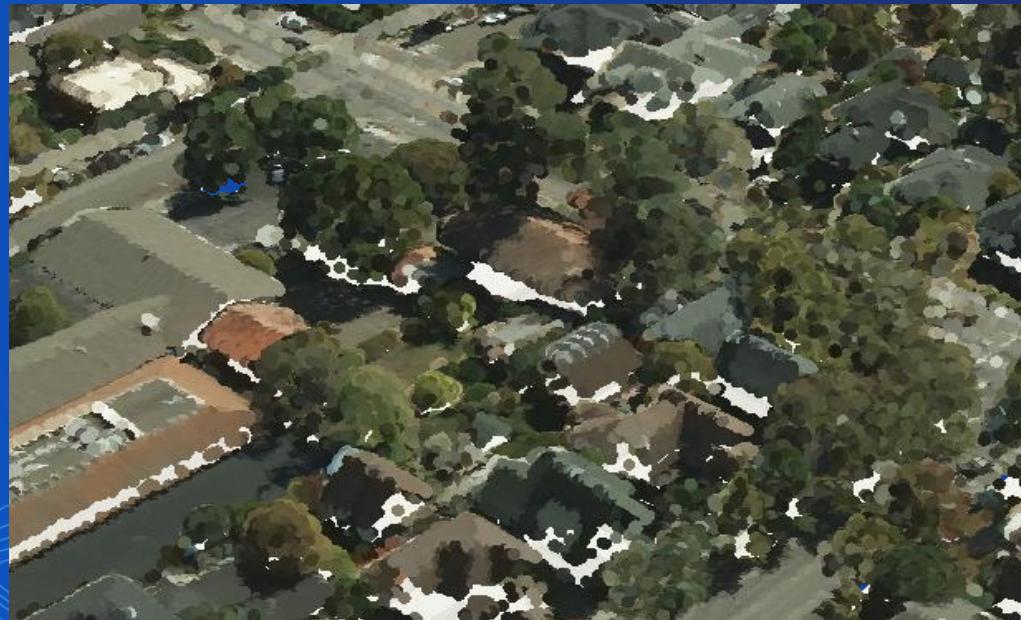
Extract LAS



Data courtesy of Optech

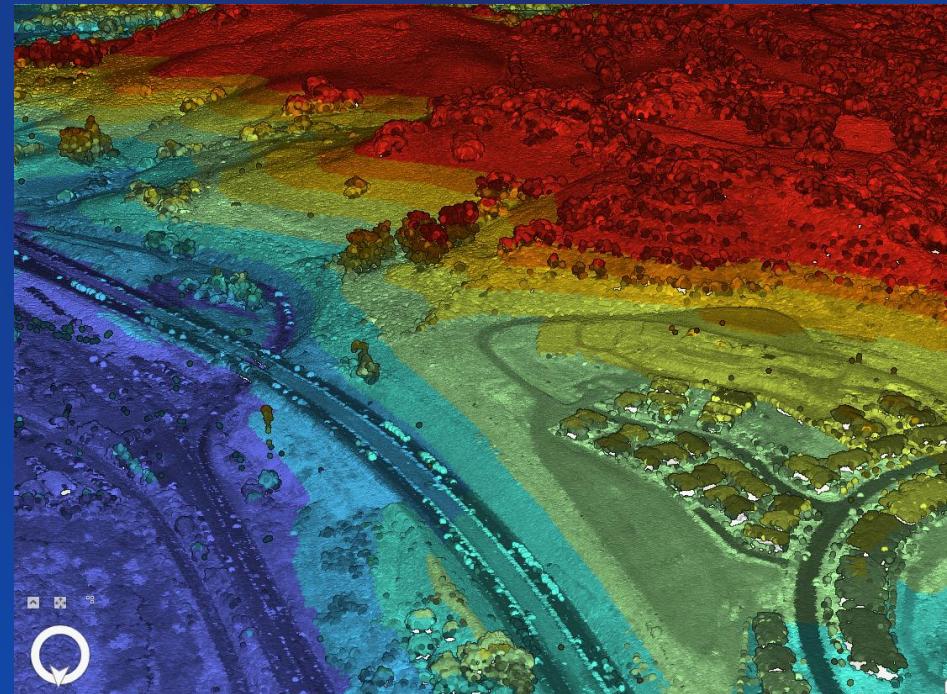
Colorize LAS

- Applies colors and near-infrared values from orthographic imagery to LAS points.
- Displaying LAS points using RGB information can provide a photorealistic display that delivers a unique display experience.



Convert LAS

- Converts LAS files between different compression methods, file versions, and point record formats.
- Convert between LAS, ZLAS, and LAZ files by selecting either the individual file, a folder containing the files to be processed, or a LAS dataset to reference a collection of LAS and ZLAS files.



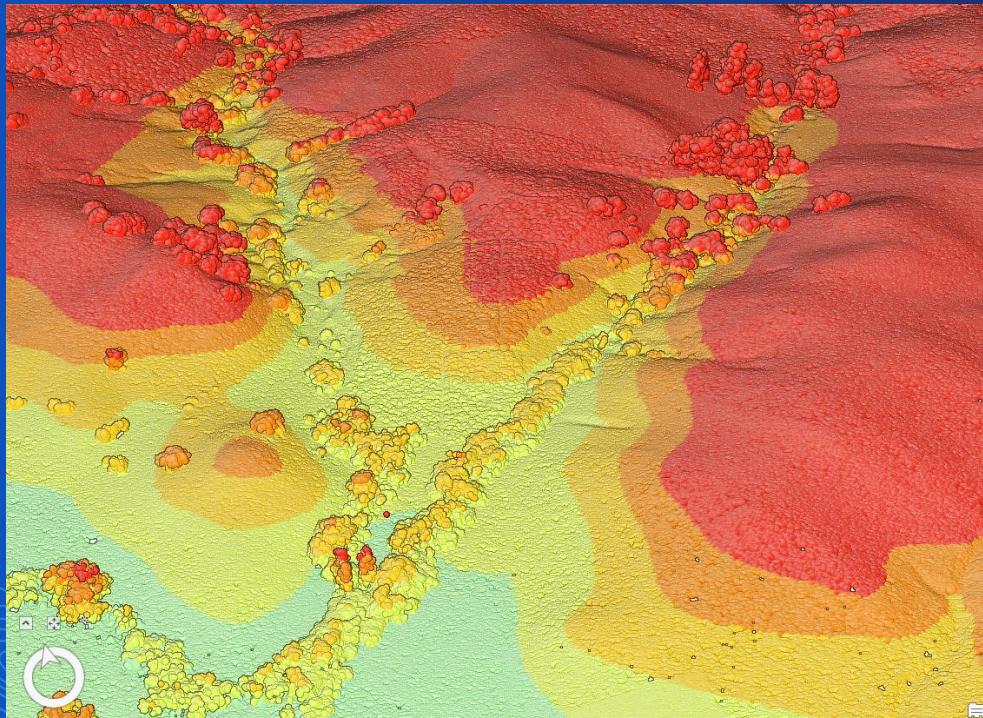
Thin LAS

- Creates new LAS files that contain a subset of LAS points from the input LAS dataset.



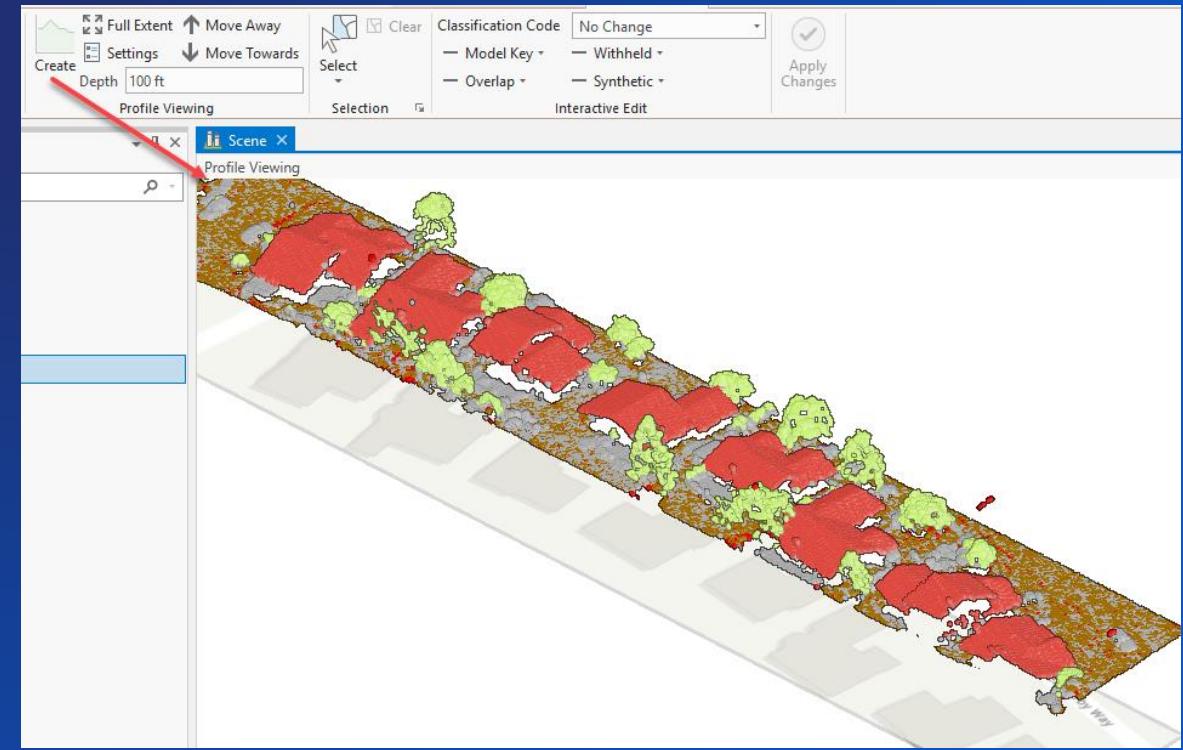
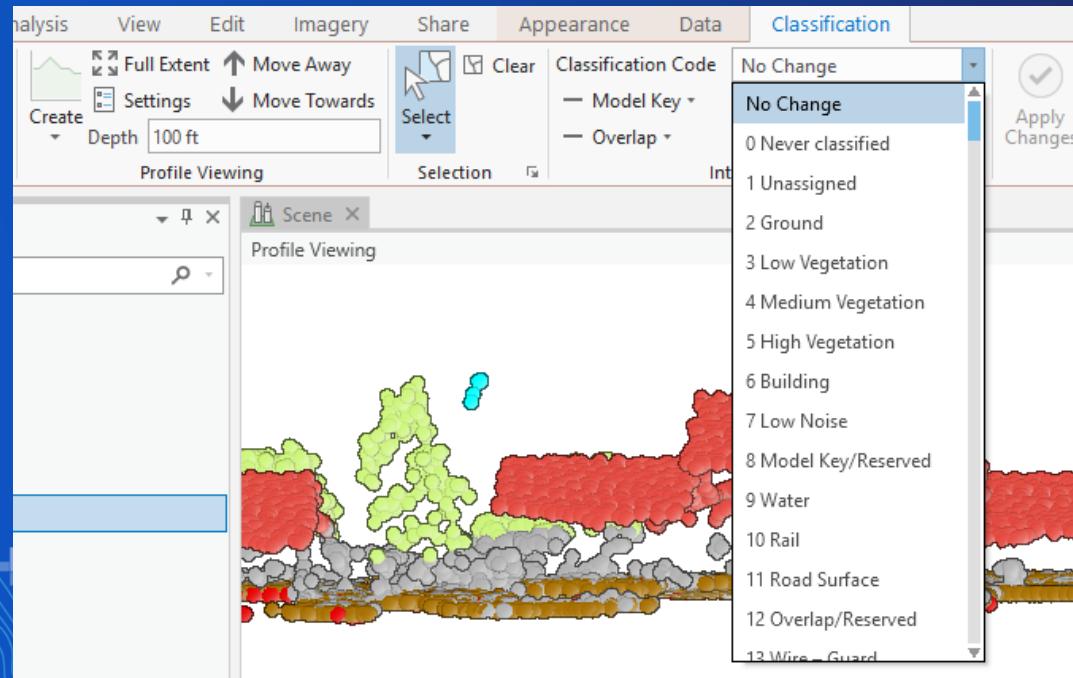
Eye-Dome Lighting

- At Pro 2.4 a new eye-dome lighting technique was added to display point clouds.
- Eye-dome lighting is a shading technique that improves depth perception when viewing lidar points in 3D.



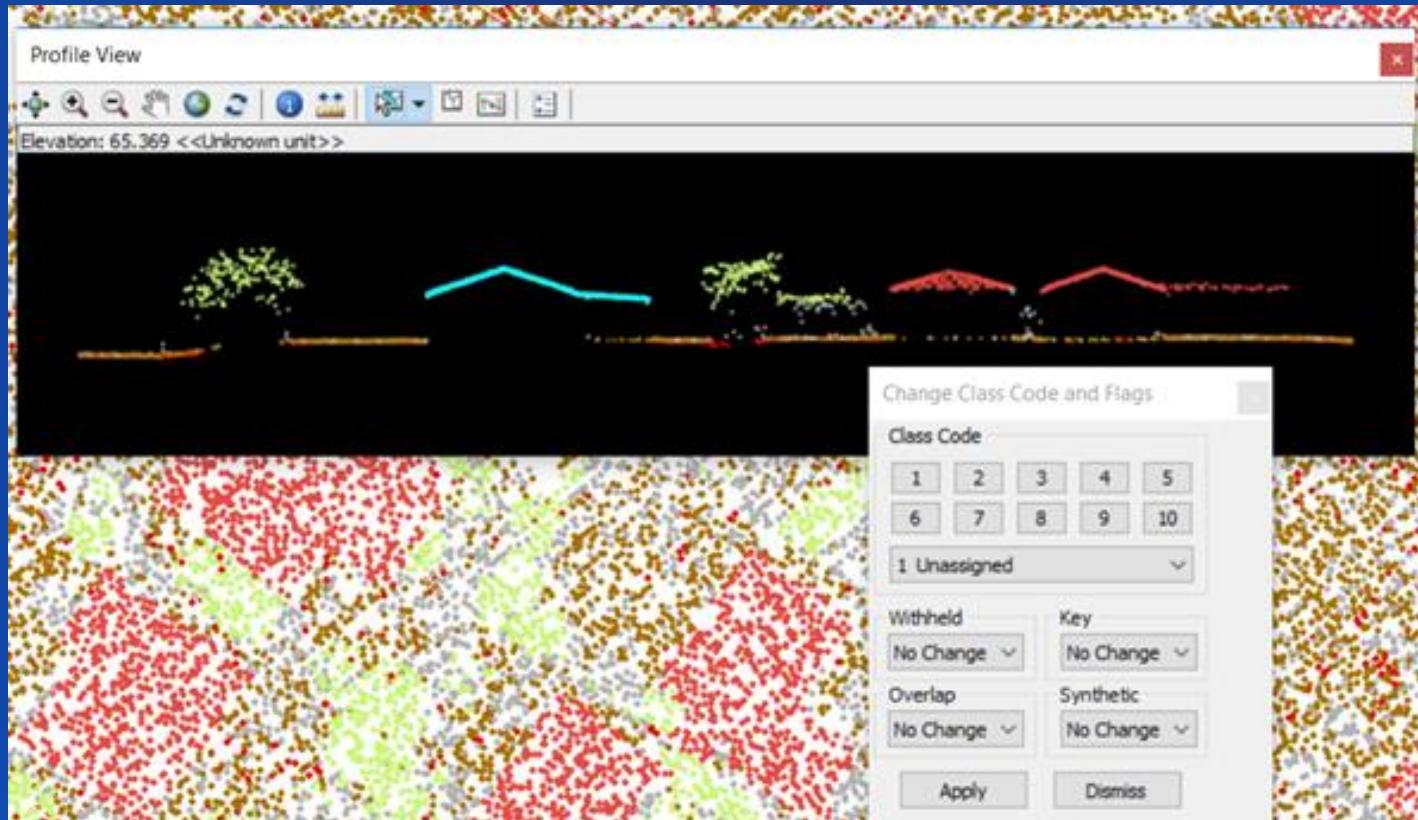
Profile Viewing: Pro

- New for 3D views is the ability to create a profile viewing state.
- For lidar this helps in fixing data anomalies and misclassifications.
- You can interactively add a profile line in the scene, and the view automatically shifts to display a vertical slice of the content.



Profile Viewing: ArcMap

- Fixing data anomalies and misclassifications via point profile window





Point Cloud Classification

Lindsay Weitz



A Variety of Choices

Fixed wing, rotary, satellite - sensors



3D Robotics – Solo



Aeryon Labs - SkyRanger



DJI – Phantom



GoPro Hero



Ultracam Vexel



WorldView-4 DigitalGlobe
Vricon



SenseFly eBee



Altavian NOVA



MicaSense RedEdge



Sony qX1

Typical Imagery Workflow

Applies to Drone Operations



Reliance on Partners

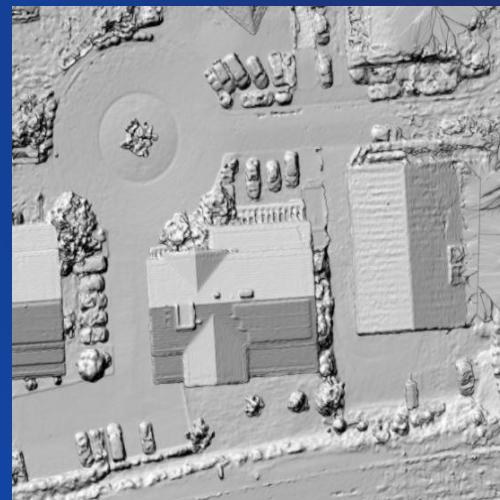
Esri Focus Area

Photogrammetric output

- Generate 2D and 3D products from raw imagery



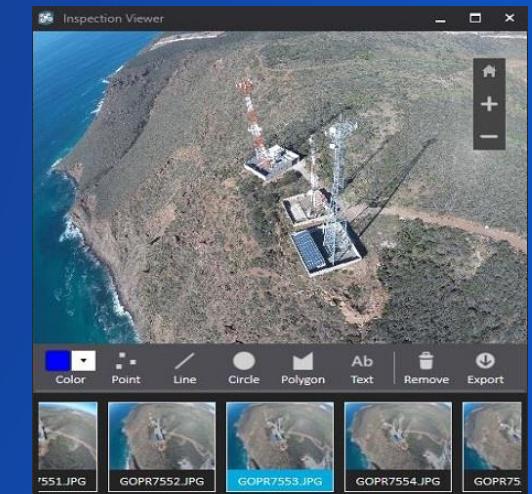
Orthomosaics



Digital Surface Models



Point Clouds and Meshes



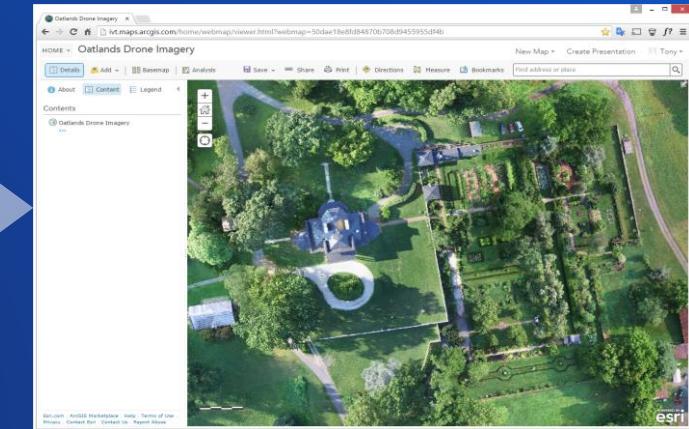
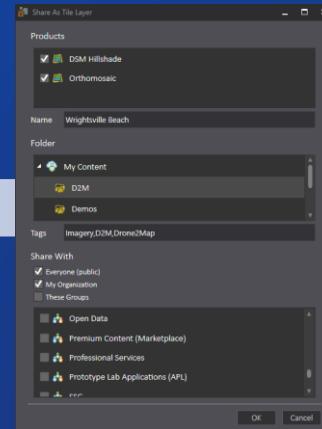
Smart Inspection

Share Imagery Fast

- Get Imagery & 3D Products To Your Users When They Need It



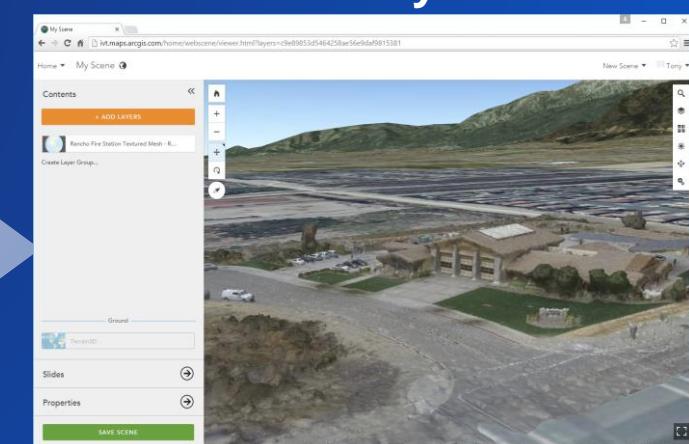
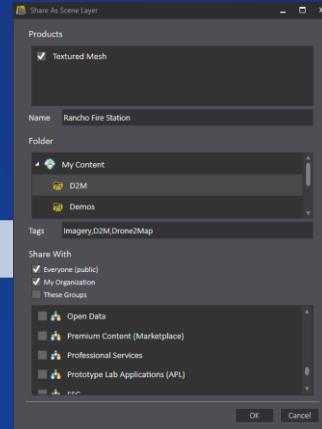
2D products



Tile Layers



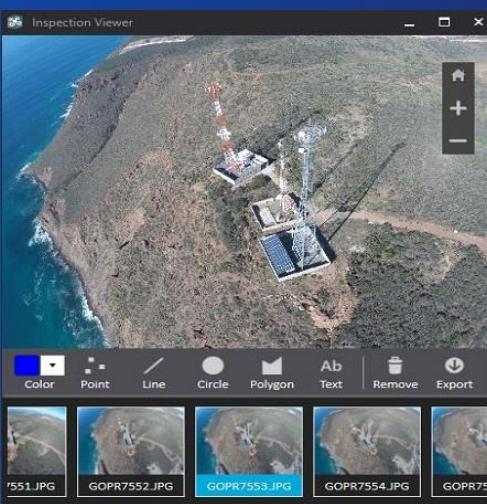
3D products



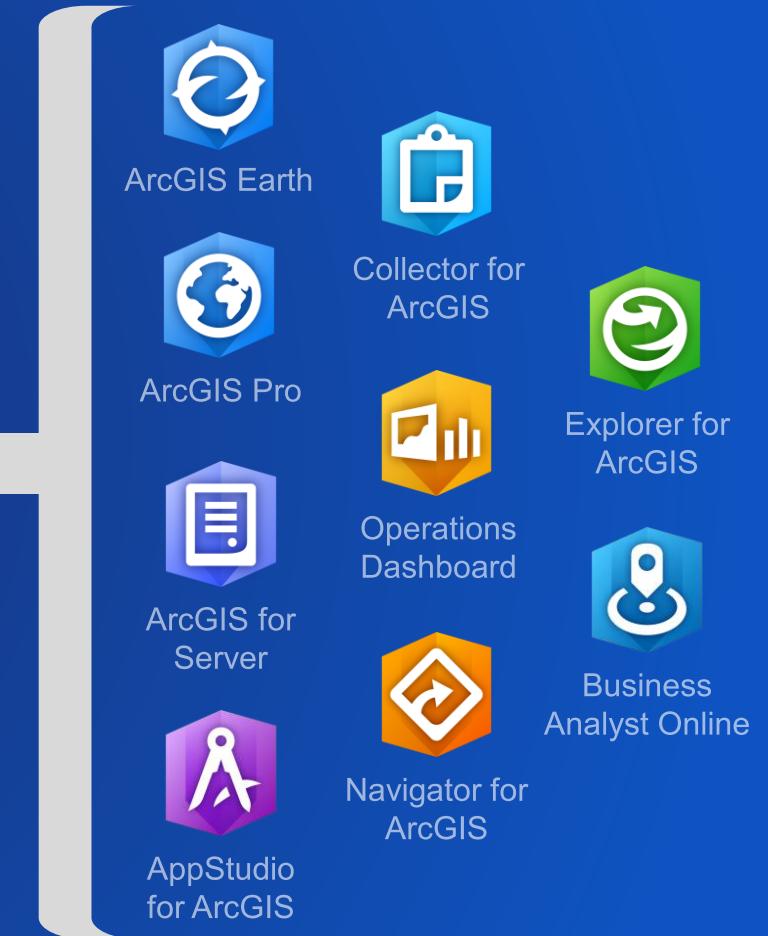
Scene layers

Using Photogrammetrically derived data With Other ArcGIS Apps

- Leverage the ArcGIS Platform for Visualization and Analysis



ArcGIS

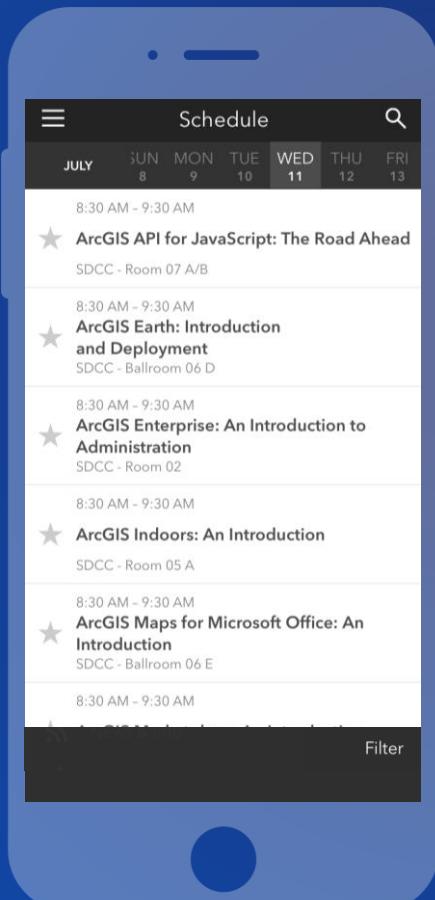


Please Take Our Survey on the App

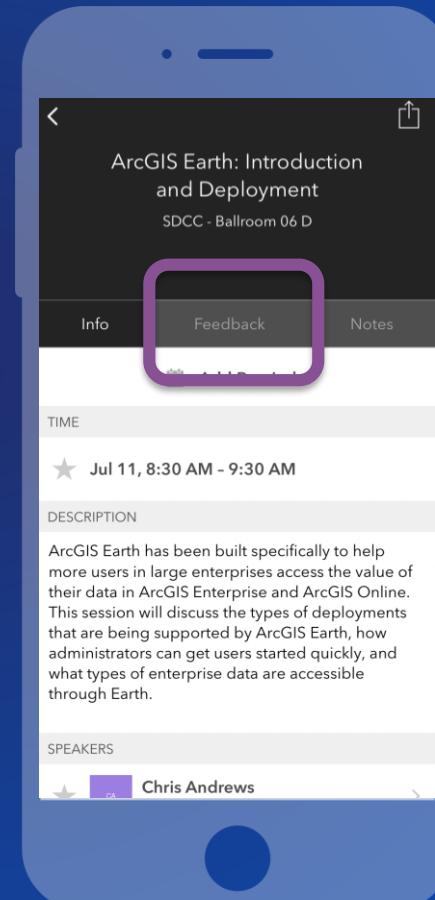
Download the Esri Events app and find your event



Select the session you attended



Select the Feedback tab



Complete answers and select "Submit"

